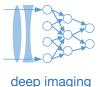


# Machine Learning and Imaging

BME 548L Roarke Horstmeyer

Lecture 7: Gradient descent and going beyond linear classification

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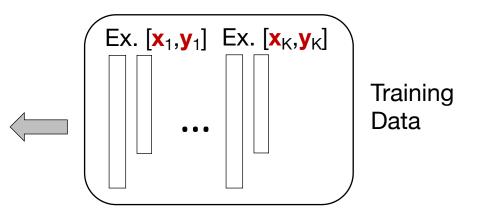
1. Network Training

What we need for network training:

1. Labeled examples

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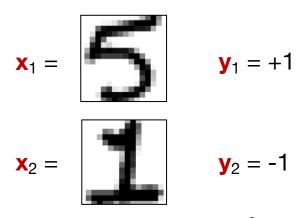




E.g., images of 1's and 5's with labels:

What we need for network training:

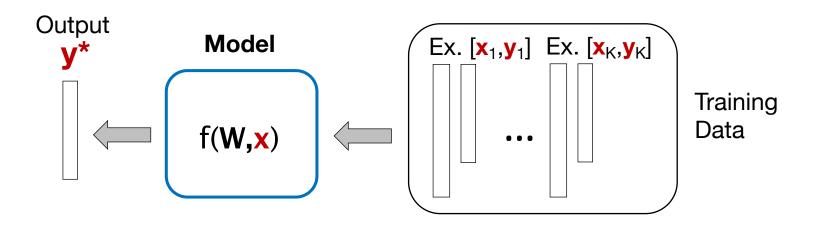
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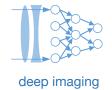


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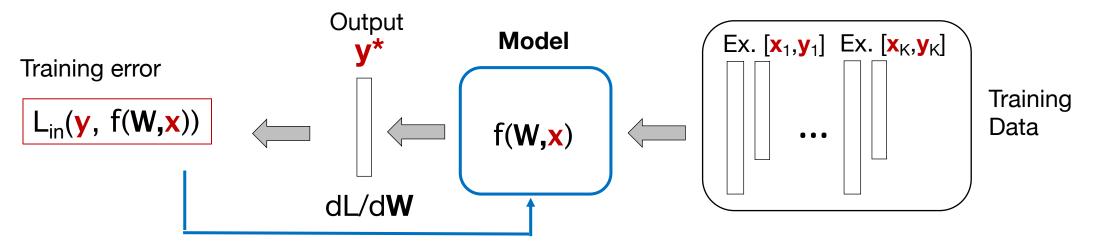


What we need for network training:

- 1. Labeled examples
- 2. A model and loss function







What we need for network training:

- 1. Labeled examples
- 2. A model and loss function
- 3. A way to minimize the loss function L



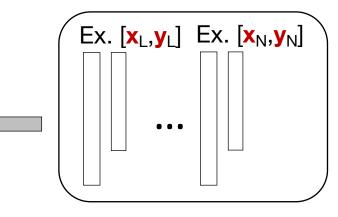
2. Network Testing

What we need for network testing:

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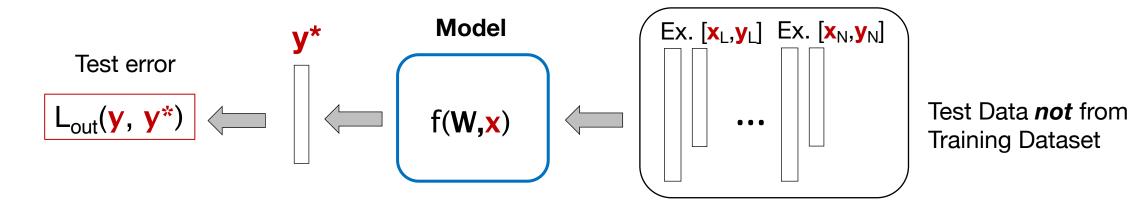
Test Data *not* from Training Dataset

What we need for network testing:

4. Unique labeled test data



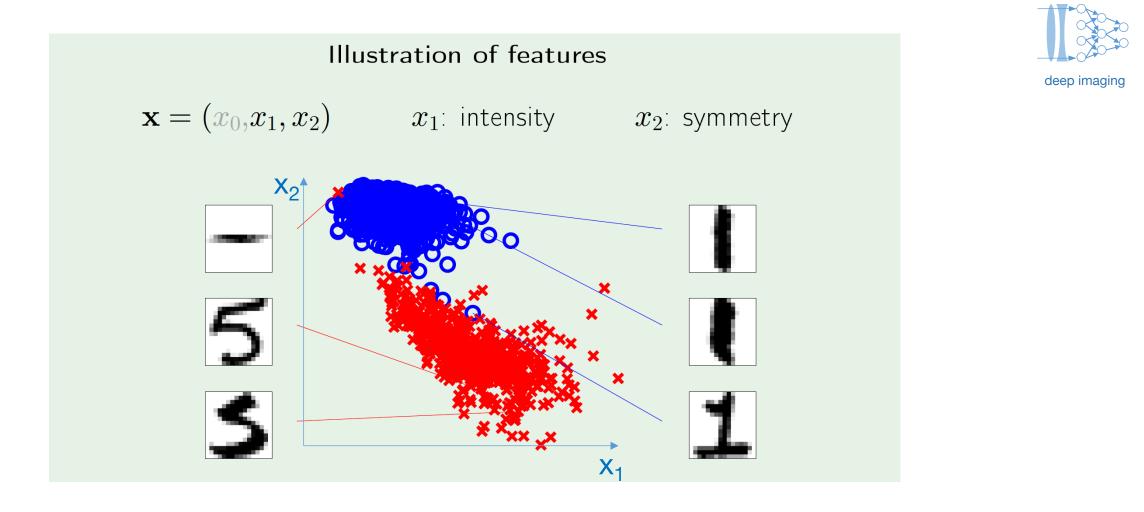
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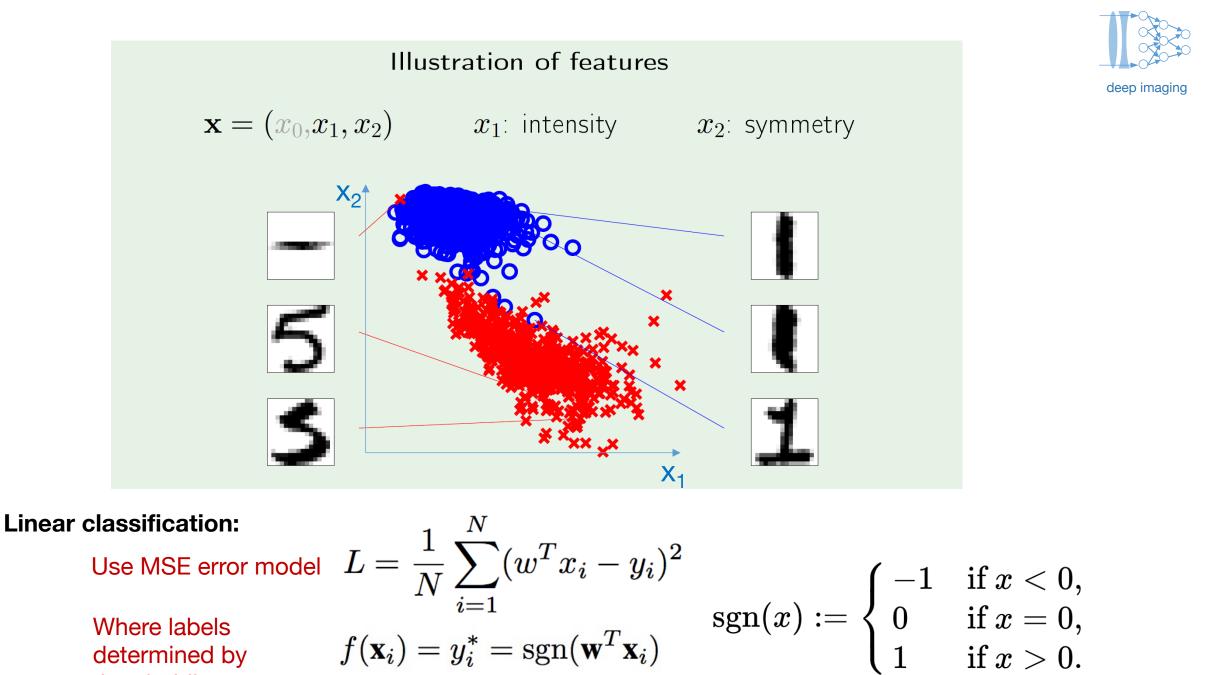
4. Unique labeled test data

5. Evaluation of model error

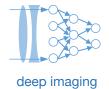


Caltech Learning from Data: <u>https://work.caltech.edu/telecourse.html</u>

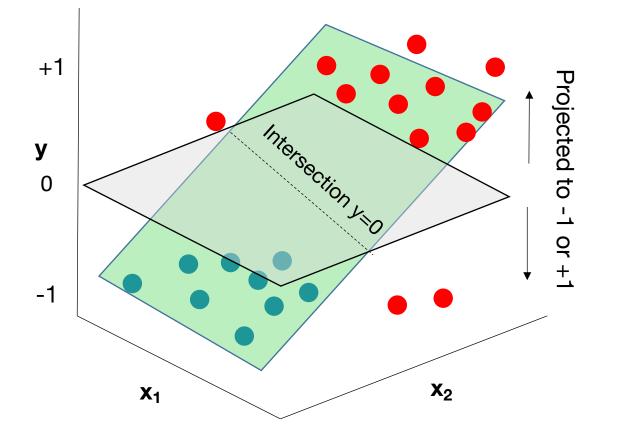
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thresholding



# Why does linear regression with sgn() achieve classification?



With sgn() operation:

$$f(\mathbf{x}_i) = y_i^* = \operatorname{sgn}(\mathbf{w}^T \mathbf{x}_i)$$
$$L = \frac{1}{N} \sum_{i=1}^N (w^T x_i - y_i)^2$$

 Anything point to one side of y=0 intersection is class +1, anything on the other side of intersection is class -1



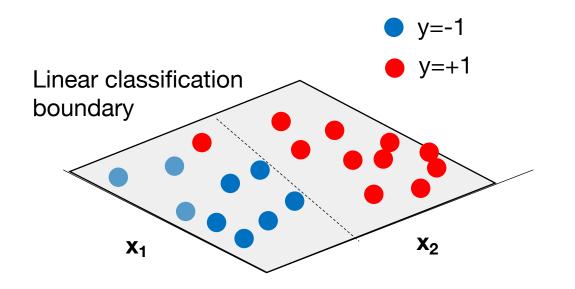
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Closed-form solution available for this boundary line **w** via pseudoinverse (see last lecture's notes)

Let's consider some other strategies to solve for **w**...





# 3 methods to solve for $w^T$ in the case of linear regression:

(easier) 1. Pseudo-inverse (this is one of the few cases with a closed-form solution)
2. Numerical gradient descent

3. Gradient descent on the cost function with respect to W

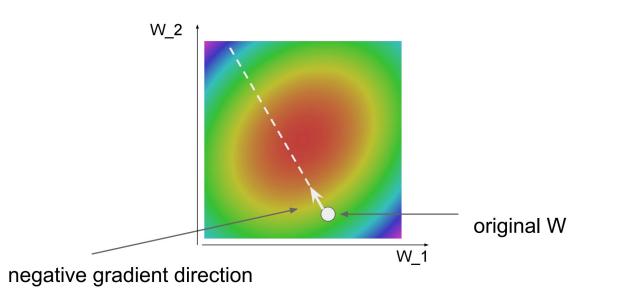
(harder)

Gradient descent: The iterative recipe



Initialize: Start with a guess of W

Until the gradient does not change very much: dL/dW = evaluate\_gradient(W, x ,y ,L) W = W - step\_size \* dL/dW evaluate\_gradient can be achieved numerically or algebraically





- 1. Evaluate function  $f(\mathbf{x}^{(0)})$  at an initial guess point,  $\mathbf{x}^{(0)}$
- 2. Compute gradient  $\mathbf{g}^{(0)} = \nabla_{\mathbf{x}} f(\mathbf{x}^{(0)})$
- 3. Next point  $\mathbf{x}^{(1)} = \mathbf{x}^{(0)} \mathbf{\varepsilon}^{(0)}\mathbf{g}^{(0)}$
- 4. Repeat:  $\mathbf{x}^{(n+1)} = \mathbf{x}^{(n)} \mathbf{\varepsilon}^{(n)}\mathbf{g}^{(n)}$ , until  $|\mathbf{x}^{(n+1)} \mathbf{x}^{(n)}| < \text{threshold t}$

```
while previous_step_size > precision and iters < max_iters:
    prev_x = cur_x
    cur_x -= epsilon * df(prev_x)
    previous_step_size = abs(cur_x - prev_x)
    **Update epsilon - see next slide
    iters+=1
```

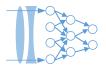
We computed this – computers can too in interesting ways

 $L = \frac{1}{N} \sum_{i=1}^{N} (w^T x_i - y_i)^2$  $\nabla L(w) = \frac{2}{N} X^T (Xw - y) = 0$ 

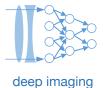
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deep imaging



What is a good step size  $\varepsilon^{(n)}$ ?



## Steepest descent and the best step size ε

What is a good step size  $\varepsilon^{(n)}$ ?

To find out, take 2<sup>nd</sup> order Taylor expansion of *f* (a good approx. for nearby points):

$$f(\boldsymbol{x}) \approx f(\boldsymbol{x}^{(0)}) + (\boldsymbol{x} - \boldsymbol{x}^{(0)})^{\top} \boldsymbol{g} + \frac{1}{2} (\boldsymbol{x} - \boldsymbol{x}^{(0)})^{\top} \boldsymbol{H} (\boldsymbol{x} - \boldsymbol{x}^{(0)})$$



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Then, evaluate at the next step:

$$f(\pmb{x}^{(0)} - \epsilon \pmb{g}) pprox f(\pmb{x}^{(0)}) - \epsilon \pmb{g}^{ op} \pmb{g} + rac{1}{2} \epsilon^2 \pmb{g}^{ op} \pmb{H} \pmb{g}$$



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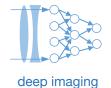
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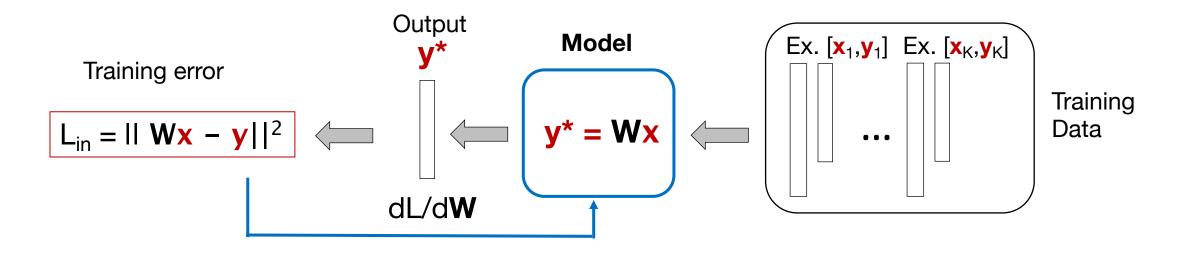
Solve for optimal step (when Hessian is positive):

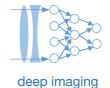
$$\epsilon^* = rac{oldsymbol{g}^ opoldsymbol{g}}{oldsymbol{g}^ opoldsymbol{H}oldsymbol{g}}.$$

J. R. Shewchuck, "An Introduction to the Conjugate Gradient Method Without the Agonizing Pain"

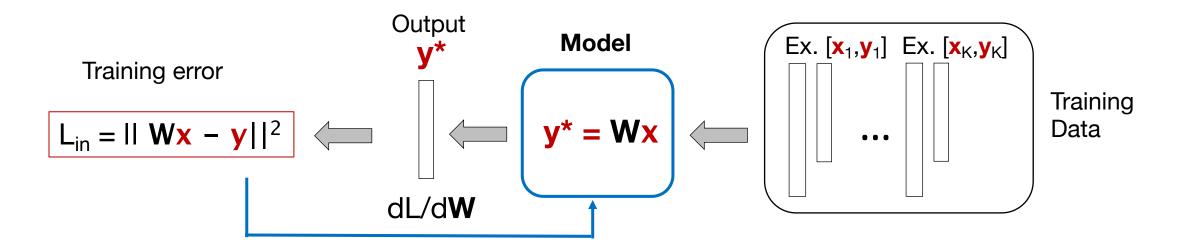


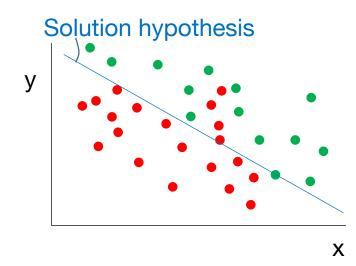
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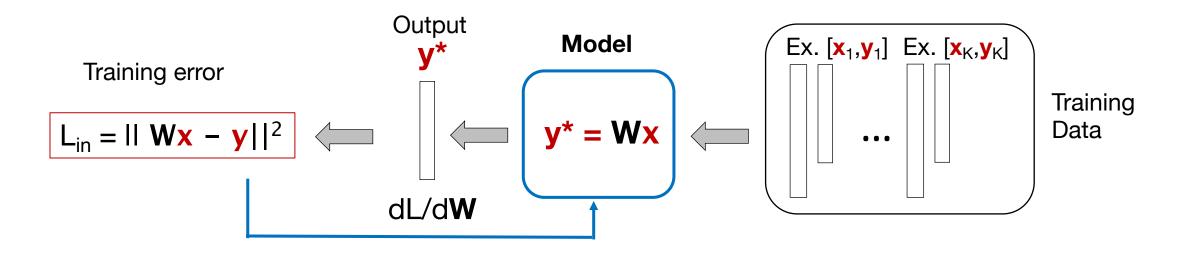


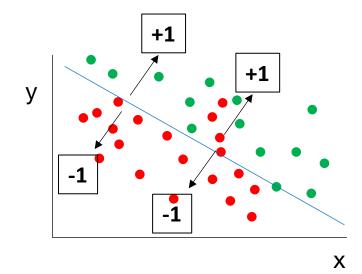


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# deep imaging

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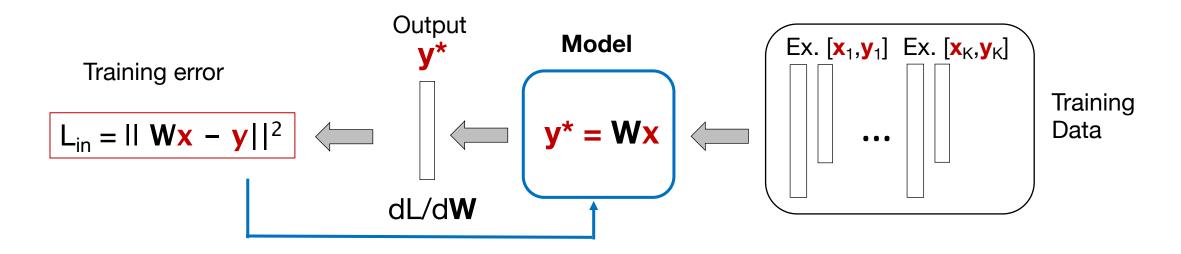


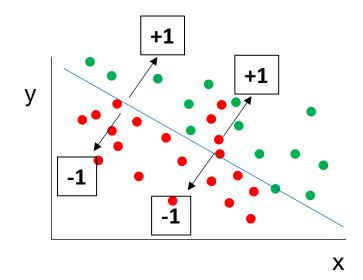


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- 2. We only allowed for binary labels (y = +/-1)

# deep imaging

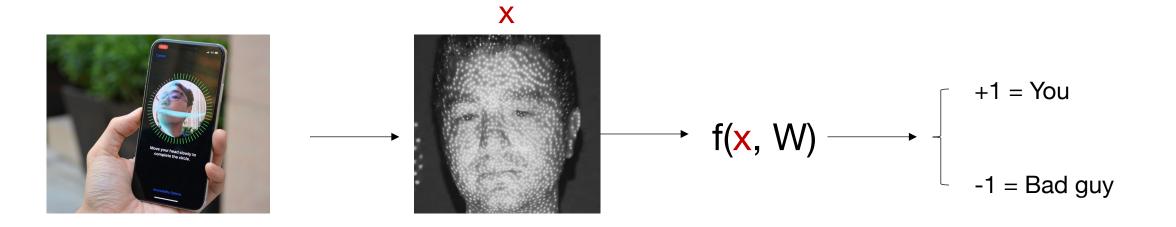
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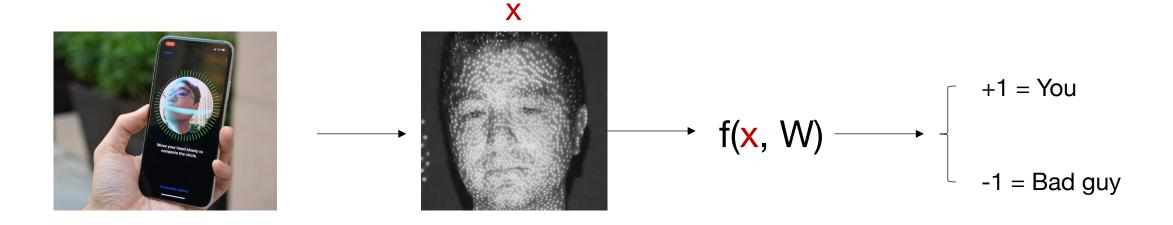




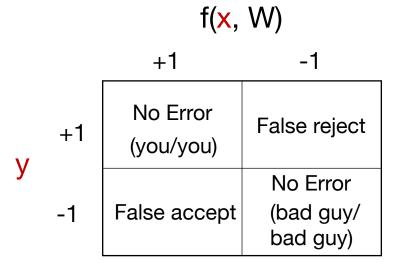
https://www.cnet.com/how-to/apple-face-id-everything-you-need-to-know/

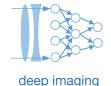
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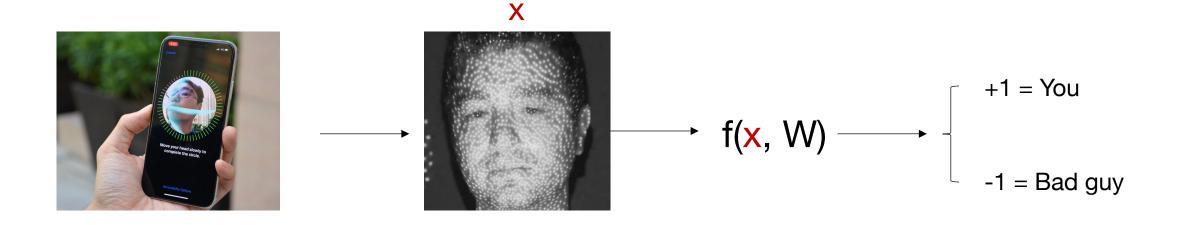




<u>Two types of error</u>: false accept and false reject

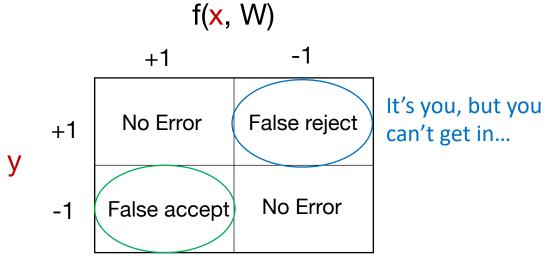




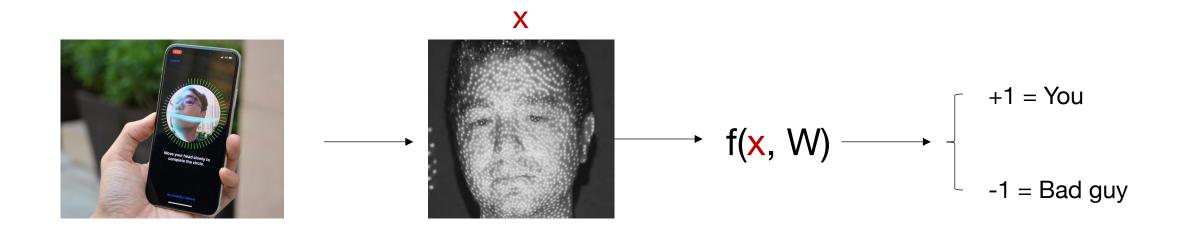


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On a standard phone, what's a good cost function?

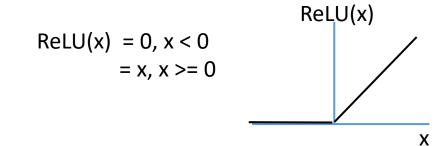




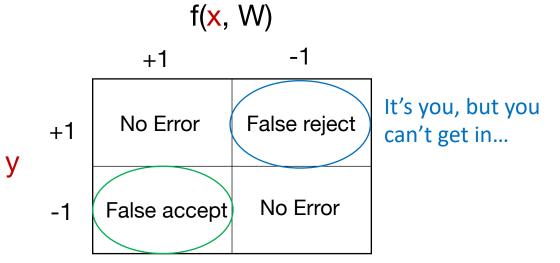


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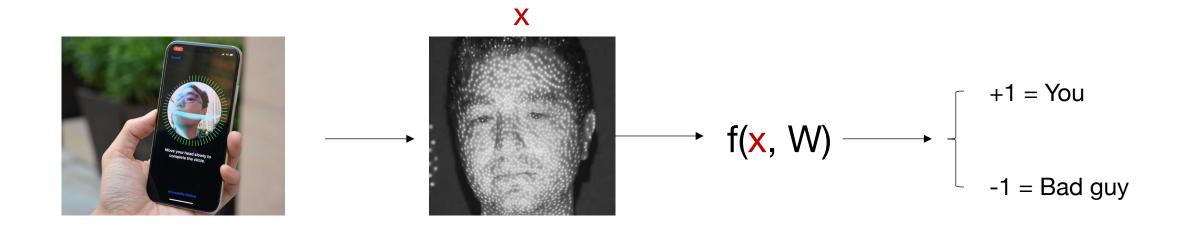
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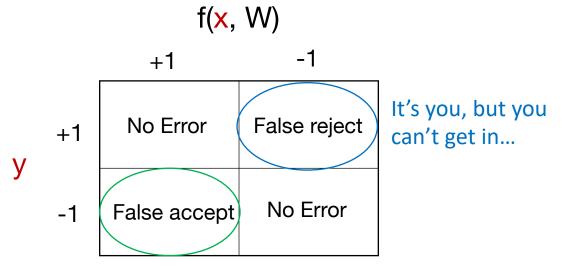


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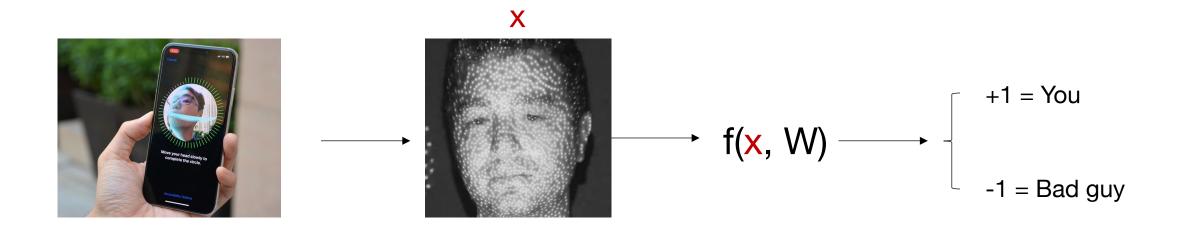
 $L_{in} = \text{ReLU}[f(x, W)-y] + 10 \text{ ReLU}[y-f(x, W)]$ 

Penalty forLarge penalty forintruderannoyance...

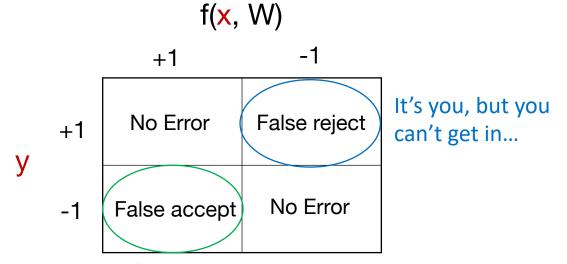


Nhttps://www.cnet.com/how-to/apple-face-id-everything-you-need-to-know/



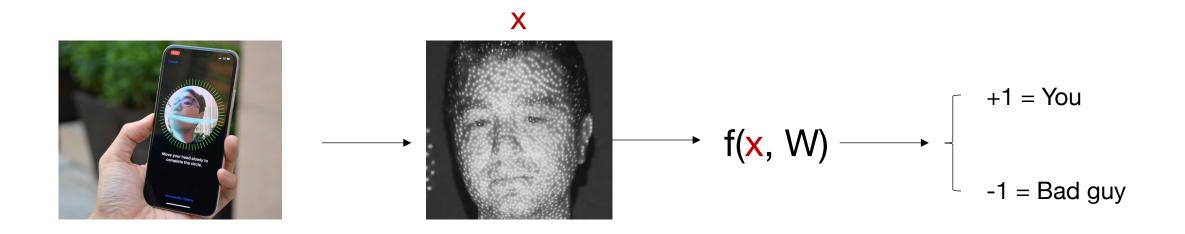


What if you're a CIA agent?



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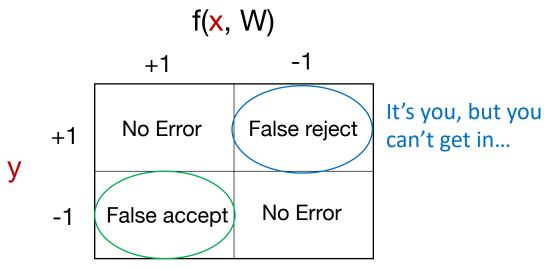


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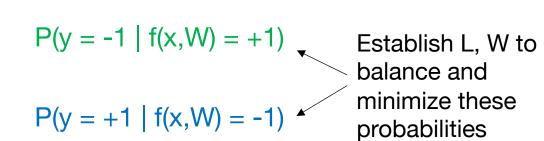
 $L_{in} = 100,000 \text{ ReLU}[f(x, W)-y] + \text{ReLU}[y-f(x, W)]$ 

BIG penalty for intruder

Don't mind about annoyance...



https://www.cnet.com/how-to/apple-face-id-everything-you-need-to-know/



Establishing cost function tied to conditional probabilities:

#### Letting an intruder in

+1

-1

У

 $f(\mathbf{x}, W)$ 

+1

$$\longrightarrow f(\mathbf{x}, \mathbf{W}) \longrightarrow \left[ \begin{array}{c} +1 = You \\ -1 = Bad guy \end{array} \right]$$

deep imaging



- Probability measures help determine when to use certain cost functions
- In previous case, we can measure probability of seeing a particular label, given model & data:

 $p(\mathbf{y}|\mathbf{w}, \mathbf{x})$ 



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• In general, to find the best model, we'd like to infer **w**, having at hand our labeled data:

Maximum Likelihood Estimation

 $p(\mathbf{w}|\mathbf{x}_1,...\mathbf{x}_N;\mathbf{y}_1,...\mathbf{y}_N)$ 



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• These two quantities are connected via Bayes' Theorem

 $p(\mathbf{w}|\mathbf{x}) = \frac{p(\mathbf{x}|\mathbf{w})p(\mathbf{w})}{p(\mathbf{x})}$ With 2 conditioned  $p(\mathbf{w}|\mathbf{x},\mathbf{y}) = \frac{p(\mathbf{x},\mathbf{y}|\mathbf{w})p(\mathbf{w})}{p(\mathbf{x},\mathbf{y})}$ variables:

 $p(\mathbf{w}|\mathbf{x}, \mathbf{y}) \propto p(\mathbf{x}, \mathbf{y}|\mathbf{w}) \propto p(\mathbf{y}|\mathbf{x}, \mathbf{w})$ 

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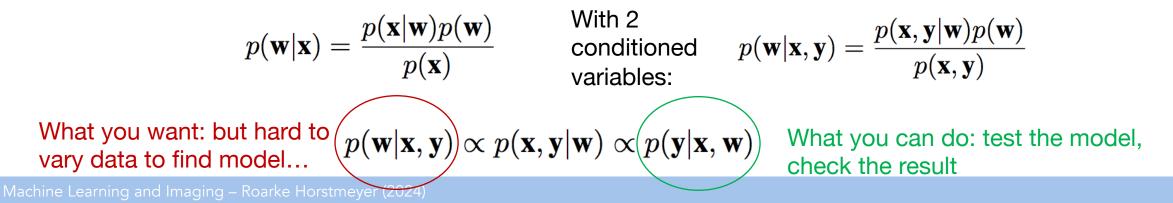
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• Given a close relationship between  $p(\mathbf{w}|\mathbf{x}, \mathbf{y}) \longleftrightarrow p(\mathbf{y}|\mathbf{x}, \mathbf{w})$ :

Maximum likelihood estimation asks the question,

For what w is  $p(\mathbf{y}_1, ..., \mathbf{y}_N | \mathbf{x}_1, ..., \mathbf{x}_N; \mathbf{w})$  maximized?



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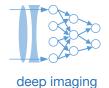
• Let's assume our labels are a "noisy" Gaussian process that surround the correct label:

$$y_i = \mathbf{w}^T \mathbf{x}_i + n$$
 (n is zero-mean Gaussian noise)

• Then, the above cond. prob. for labels can be expressed as a multivariate Gaussian



For what **w** is 
$$\prod_{i=1}^{N} p(\mathbf{y}_i, |\mathbf{x}_i, \mathbf{w})$$
 maximized?  
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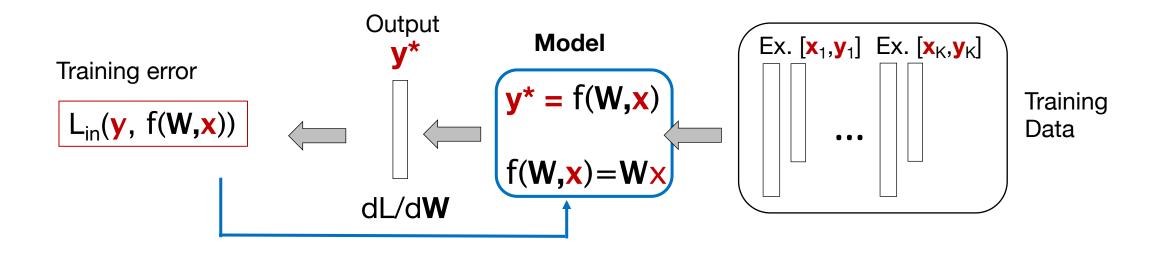


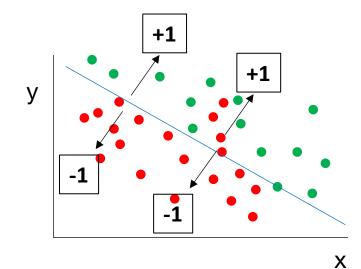
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Summary: Linear classification with MSE assumes model output deviates from true labels via a Gaussian random process. Is this fair, given that labels are ether -1 or +1?

# deep imaging

# The linear classification model – what's not to like?

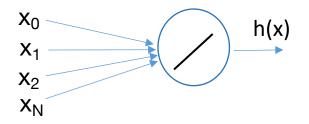




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deep imaging

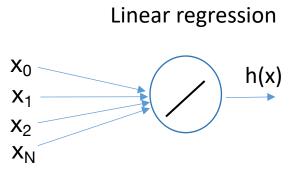
Linear regression: predict some output h(x) from x



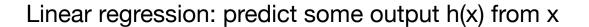


Linear regression: predict some output h(x) from x

$$h(x) = x \in (-\infty, \infty)$$



Not a probabilistic mapping

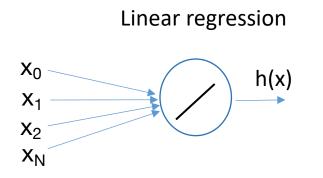


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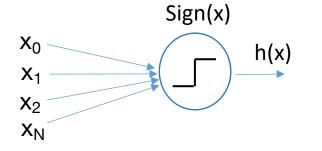
Linear classifier: predict binary output h(x) from x

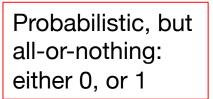
$$h(x) = \operatorname{sign}(w_o^T x_j)$$

$$h(x) = \operatorname{sign}(x) \in \{0, 1\}$$



Not a probabilistic mapping

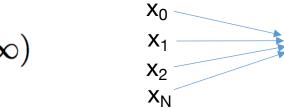






Linear regression:

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Not a probabilistic mapping

Linear regression

h(x)

h(x)

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->

 $(w_o^T x_j)$   $x_0$   $x_1$   $x_2$   $x_2$   $x_N$   $\theta(x)$   $x_0$   $\theta(x)$ 

**X**<sub>2</sub>

X<sub>N</sub>

Probabilistic, but all-or-nothing: either 0, or 1

Probabilistic: continuous value between 0 and 1

Linear classifier:

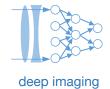
$$h(x) = \operatorname{sign}(w_o^T x_j)$$
$$h(x) = \operatorname{sign}(x) \in \{0, 1\}$$

Logistic classifier:

$$h(x) = \theta(x) \in [0, 1]$$

Any value between 0 and 1





Probabilistic interpretation of function that maps outputs to labels,  $h(x) = \theta(x)$ 

**Example**: You are trying to predict the probability that a patient may have a certain form a disease,  $\theta(\mathbf{x})$ , given a number of observations and measurements,  $\mathbf{x}$ 

**Example**: You are trying to predict the probability of rain tomorrow,  $\theta(\mathbf{x})$ , given a set of satellite image data,  $\mathbf{x}$ 

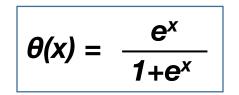


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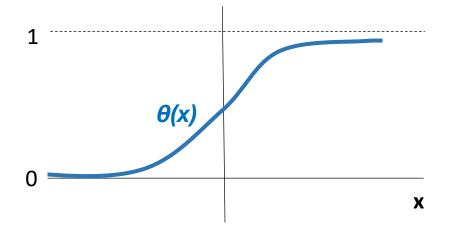
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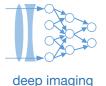
The Logistic Function  $\boldsymbol{\theta}$ 



Also called Sigmoid function



- Use soft threshold to map any number to [0,1] range
- Sigmoid "flattens out" x

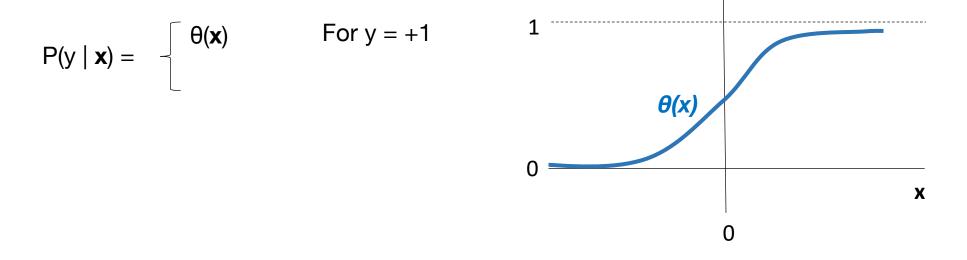


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- map these binary values onto a [0,1] probability distribution

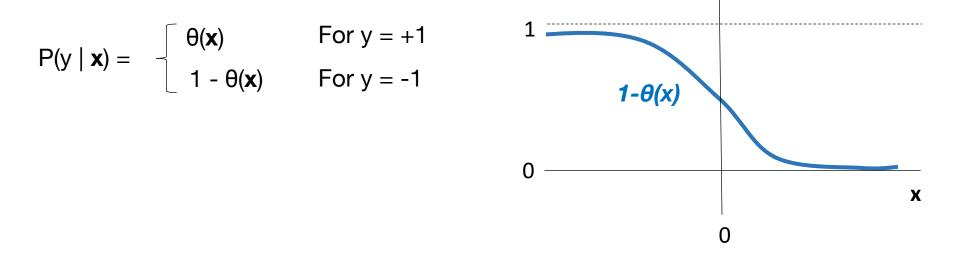


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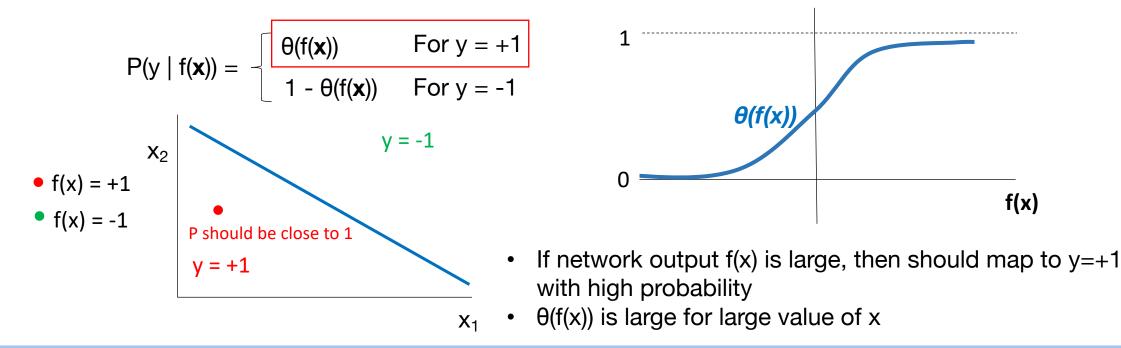


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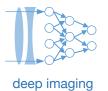
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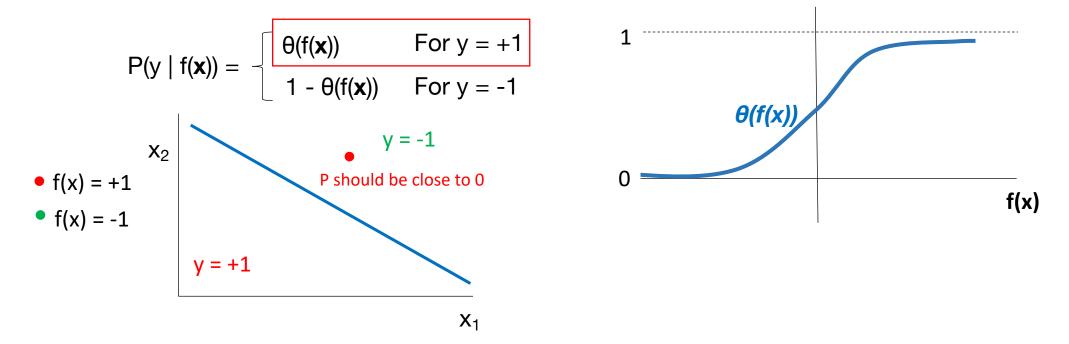
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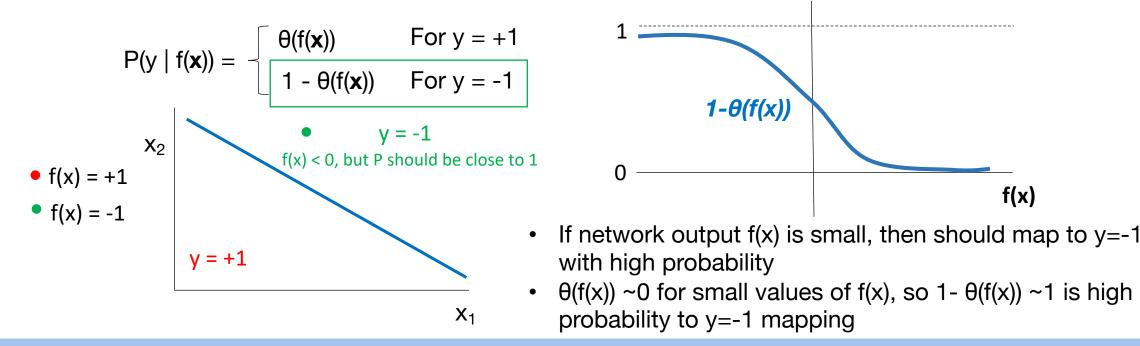


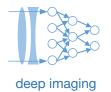
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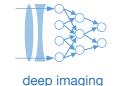




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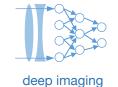






Instead of mapping  $f(\mathbf{x})$  to either +1 or -1 with the sign operator, let's use  $\theta$  to map it to lie between 0 and 1:

$$P(y \mid \mathbf{x}) = \begin{cases} \theta(f(\mathbf{x})) & \text{For } y = +1 \\ 1 - \theta(f(\mathbf{x})) & \text{For } y = -1 \end{cases}$$



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So, we can summarize the case-based definition above with a single function,

 $\mathsf{P}(\mathsf{y} \mid \mathbf{x}) = \theta(\mathsf{y} \mathsf{f}(\mathbf{x}))$ 



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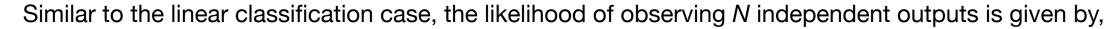
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So, we can summarize the case-based definition above with a single function,

 $P(y \mid \mathbf{x}) = \theta(y \ f(\mathbf{x}))$  $P(y \mid \mathbf{x}) = \theta(y \ \mathbf{w}^{\mathsf{T}}\mathbf{x})$ 

Here, y = +/-1 flips  $\theta(\mathbf{w}^T \mathbf{x})$  to be either  $\theta(\mathbf{w}^T \mathbf{x})$  or  $\theta(-\mathbf{w}^T \mathbf{x}) = 1 - \theta(\mathbf{w}^T \mathbf{x})$ 



$$P(\mathbf{y}_1, \mathbf{y}_2... \mathbf{y}_N \mid \mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_N) = \prod_{n=1}^{N} P(\mathbf{y}_n \mid \mathbf{x}_n)$$
$$= \prod_{n=1}^{N} \Theta(\mathbf{y}_n \ \mathbf{w}^{\mathsf{T}} \mathbf{x}_n)$$

This is the probability of the labels, given the data. We'd like to maximize this probability!

\*Like the linear regression case, but now the probability of classes given the data is not Gaussian distributed, but instead follows the sigmoid curve (is bound to [0,1], which is more realistic)

Maximize 
$$P(y_1, y_2... y_N | \mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_N) = \prod_{n=1}^N \theta(y_n \mathbf{w}^T \mathbf{x}_n)$$



# deep imaging

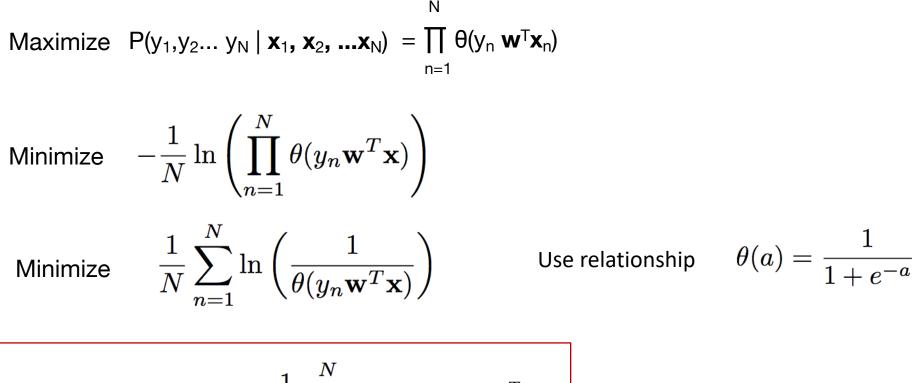
#### Deriving cost function for logistic classification for probabilistic outputs

Maximize 
$$P(y_1, y_2..., y_N | \mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_N) = \prod_{n=1}^{N} \theta(y_n \mathbf{w}^T \mathbf{x}_n)$$

Minimize 
$$-\frac{1}{N}\ln\left(\prod_{n=1}^{N}\theta(y_{n}\mathbf{w}^{T}\mathbf{x})\right)$$

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Minimize  $-\frac{1}{N} \ln \left( \prod_{n=1}^{N} \theta(y_n \mathbf{w}^T \mathbf{x}) \right)$   
Minimize  $\frac{1}{N} \sum_{n=1}^{N} \ln \left( \frac{1}{\theta(y_n \mathbf{w}^T \mathbf{x})} \right)$  Use relationship  $\theta(a) = \frac{1}{1 + e^{-a}}$ 



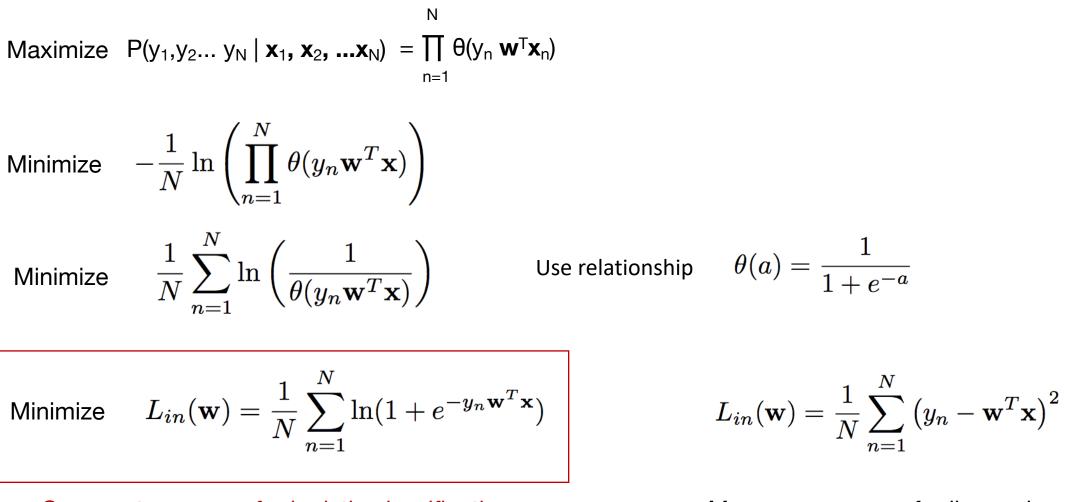


deep imaging

Minimize 
$$L_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} \ln(1 + e^{-y_n \mathbf{w}^T \mathbf{x}})$$

Cross entropy error for logistic classification

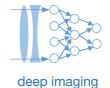
Typically requires iterative solution to minimize



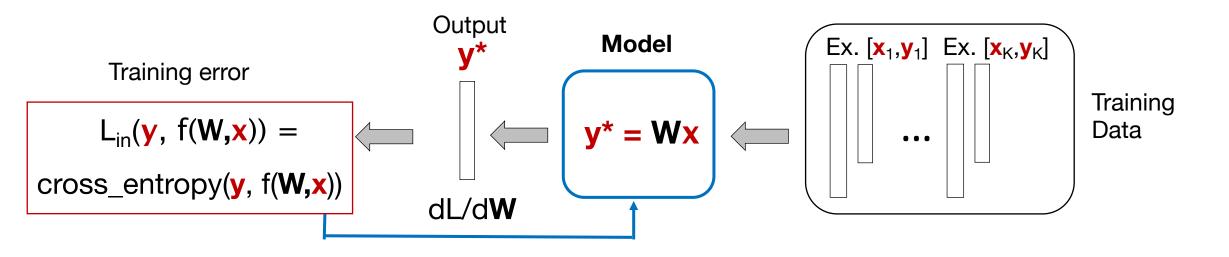
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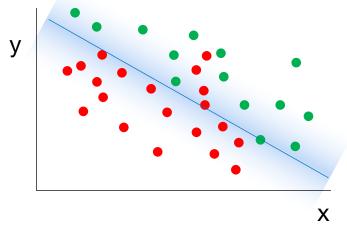
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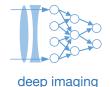


# The linear classification model – what's not to like?

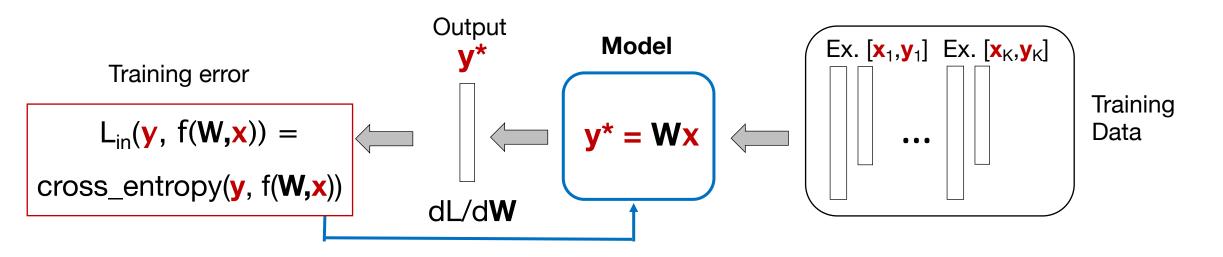


Probabilistic mapping to y

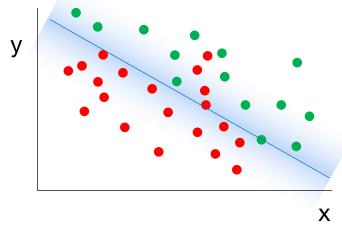




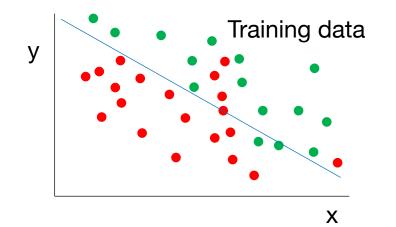
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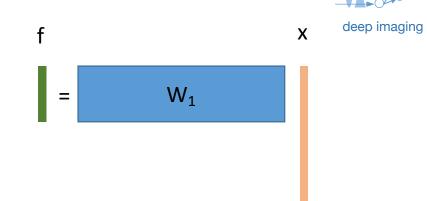


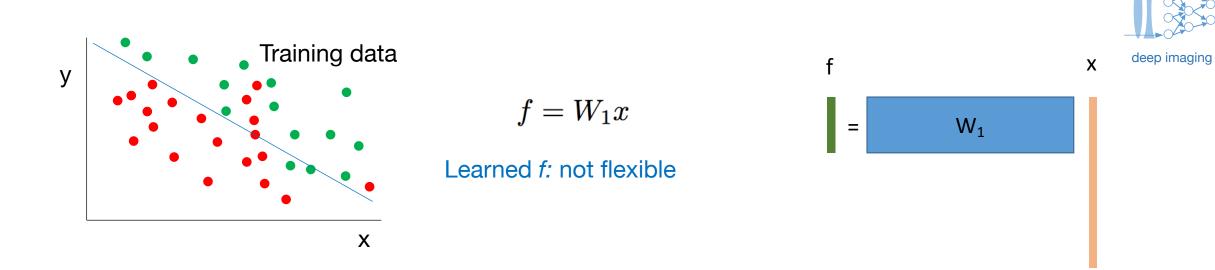
- 1. Can only separate data with lines (hyper-planes)...
- 2. We only allowed for binary labels (y = +/-1)
- 3. Error function L<sub>in</sub> inherently makes assumptions about statistical distribution of data



 $f = W_1 x$ 

Learned *f*: not flexible



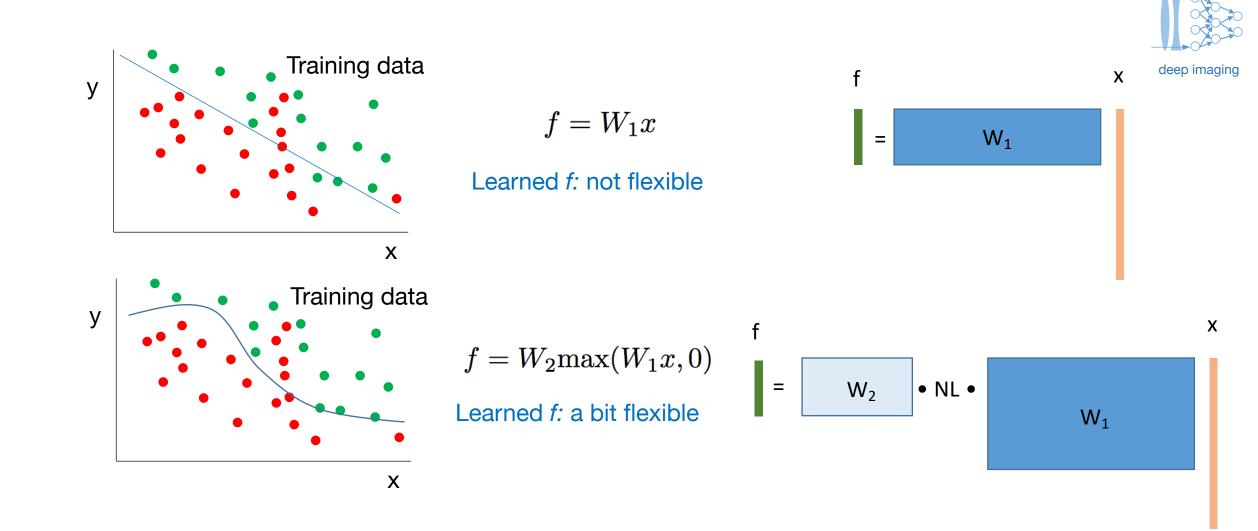


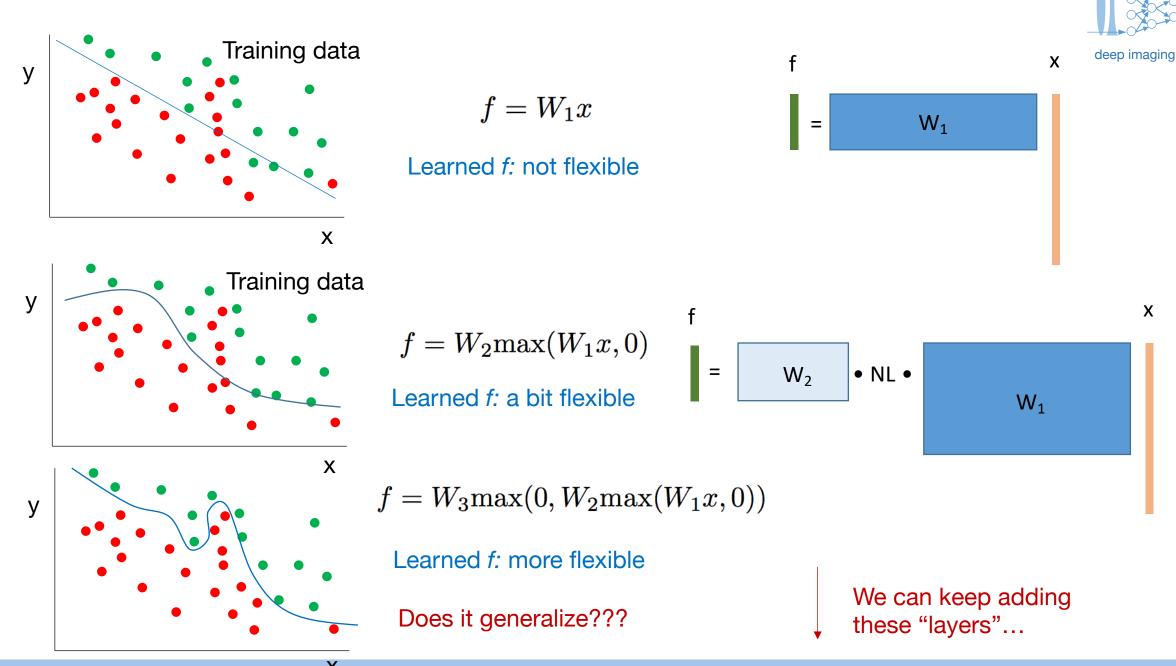
Can we add flexibility by multiplying with another weight matrix?

$$\begin{bmatrix} f_1 = W_1 x + b_1 & f & f \\ f_2 = W_2 f_1 + b_2 & \bullet \end{bmatrix} = W_2 \quad W_1$$

$$f_2 = W_2 (W_1 x + b_1) + b_2$$

$$f_2 = W' x + b' \quad \text{Unfortunately not...}$$

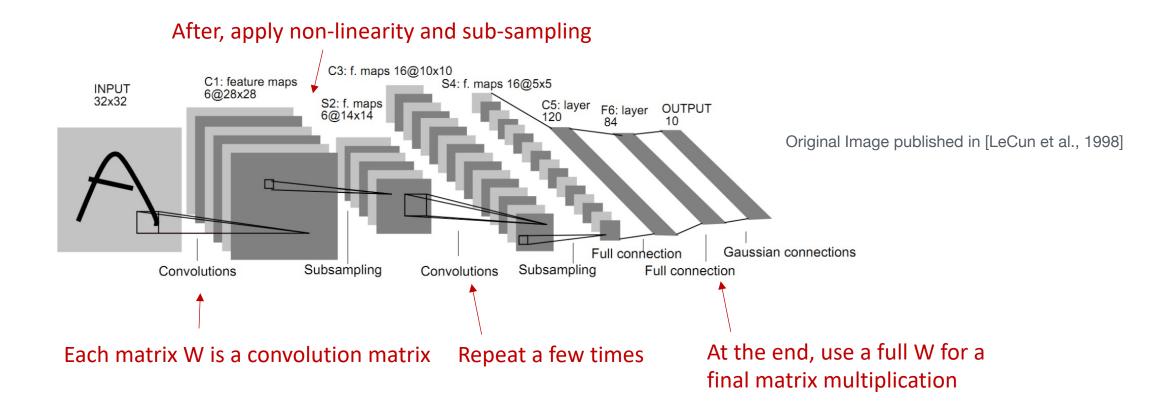




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